





Enquiry N°: Created by/Checked by: WT/HO

SERVO MOTOR 142LDA200

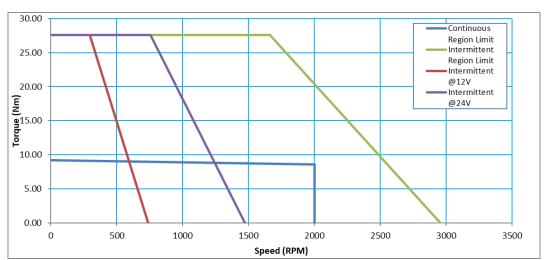
2000KG PAYLOAD AGV SOLUTION



| Definition | | | | | | |
|----------------------------|-------------|---|--|--|--|--|
| Туре | Unimotor HD | | | | | |
| Frame Size (mm) | 142 | | | | | |
| Voltage | L | 40-50 Vdc | | | | |
| Magnet type | D | High Dynamic | | | | |
| Frame Length | Α | | | | | |
| Speed (min ⁻¹) | 20 | 2000 | | | | |
| Brake | 0 | Unbraked | | | | |
| Connection type | F | Power and Signal flying leads (0.5 m) | | | | |
| Output shaft | G | Gearbox output | | | | |
| Feedback device code | CJ | Renco R35i encoder 4096 5PP push-pull comms | | | | |
| Inertia & thermistor | Н | High Inertia + no thermistor | | | | |
| PCD (Gearbox) | 165 | 165 (FF 165/90) | | | | |
| Shaft Diameter (Gearbox) | 900 | 90 mm register diameter | | | | |
| Insulation class | F | | | | | |
| UL Motor / UL Stator | UL Stator | | | | | |

| Nominal characteristics | | | | | | |
|------------------------------------|------|-------------------------------|-------|--|--|--|
| Motor Ambient Temperature (°C) | 40 | Drive Fsw (kHz) | 12 | | | |
| Motor Peak Torque (Nm) | 27.6 | Stall Current (A) | 44.0 | | | |
| Motor Stall Torque (Nm) | 9.2 | Rated Current (A) | 41.1 | | | |
| Rated Torque (Nm) | 8.6 | Kt (Nm/A) | 0.209 | | | |
| Rated Power (kW) | 1.8 | Ke (V/kmin ⁻¹) | 12.8 | | | |
| Winding Thermal Time Constant (s) | 235 | R (ph-ph) (Ohm) | 0.02 | | | |
| Number of Poles | 10 | L (ph-ph) (mH) | 0.22 | | | |
| Typical Cogging (Nm) | 0.05 | | | | | |
| Inertia (kg.cm²) (Motor + Gearbox) | ≈ 86 | Weight (kg) (Motor + Gearbox) | ≈ 13 | | | |
| Ingress Protection Level (IP) | IP54 | | | | | |

Torque / speed graph



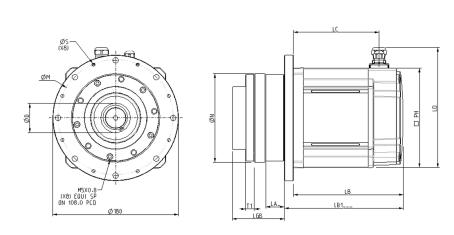




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Motors (° & mm)



| LB | Total length (Motor) | 174.6 |
|-----|---------------------------------|-------|
| LB1 | length with Gearbox flange | tbc |
| LC | Power connector position | 139.7 |
| LGB | Gearbox Length | 87.5 |
| LA | Flange to Flange (Gearbox) | 25.5 |
| T1 | Register Length (Gearbox) | 14.0 |
| N | Register Diameter (Gearbox) | 127.0 |
| LD | Power connector overall height | 179.5 |
| LD1 | Signal connector overall height | 166.6 |
| S | Fixing Hole Diameter (Gearbox) | M5 |
| М | Fixing hole PCD (Gearbox) | 165 |
| PH | Motor Housing Width | 142 |
| LB | Mounting Bolt (Gearbox) | M5 |
| | Total Motor Length Inc. Gearbox | 262.1 |

Motor electrical interface 0.5m flying leads option:

| Feedback device code: CJ – Renco R35i encoder 4096 5PP push-pull comms | | | | ns | Connection type: F – Power and Signal flying leads (0.5 m) | | | |
|---|-------|--------|----|--------|---|---|-------|--------------------|
| 1 | Red | + V | 7 | Yellow | CH A | 1 | U | Orange (x 2) |
| 2 | Green | HALL A | 8 | - | - | 2 | V | Red (x 2) |
| 3 | Brown | HALL B | 9 | Blue | CH B | 3 | W | Yellow (x 2) |
| 4 | White | HALL C | 10 | - | - | 4 | Earth | Green/Yellow (x 2) |
| 5 | Black | 0 V | 11 | - | - | | | |
| 6 | _ | - | 12 | - | - | | | |

Power connection: 0.5 m flying lead, M20 gland

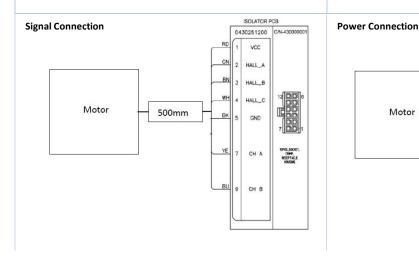
8 cores of 12 AWG UL 1330 wire, with polyolefin heat-shrink sleeve;

M6 Ring terminals fitted to lead wires

Signal connection: 0.5 m flying lead, M16 gland

7 cores of 28 AWG PVC wire, insulated in UL AWM 2725 PVC jacket, screened;

12-Way Molex connector 43025-1200 (see opposite for pin detail)



Motor 500mm OG OU1 GN OEG

M6 Ring Terminals

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→ All for dreams

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| Gearbox characteristics | | | | | | |
|-------------------------|------------------|---|-------|--|--|--|
| | | | | | | |
| Manufacturer | Shimpo | Backlash (arc/min) | ≤ 8 | | | |
| Туре | Inline Planetary | Radial Load (Fr, N) @ Fa=0, Input Speed Nom | 6900 | | | |
| Part No. | VRLZ-120-9-340 | Radial Load MAX (Fr, N) | 10000 | | | |
| Ratio | 9 | Axial Load (Fa, N) @ Fr=0, Input Speed Nom | 3800 | | | |
| Stages | 1 | Output Torque Nominal (Nm) | 90 | | | |
| Inertia (kg.cm²) | ≈ 72 | Output Torque Max (Nm) | 225 | | | |
| Weight (kg) | 6.6 | Input Speed Nom (rpm) | 2000 | | | |
| Efficiency | 95% | Input Speed Max (rpm) | 3000 | | | |

